

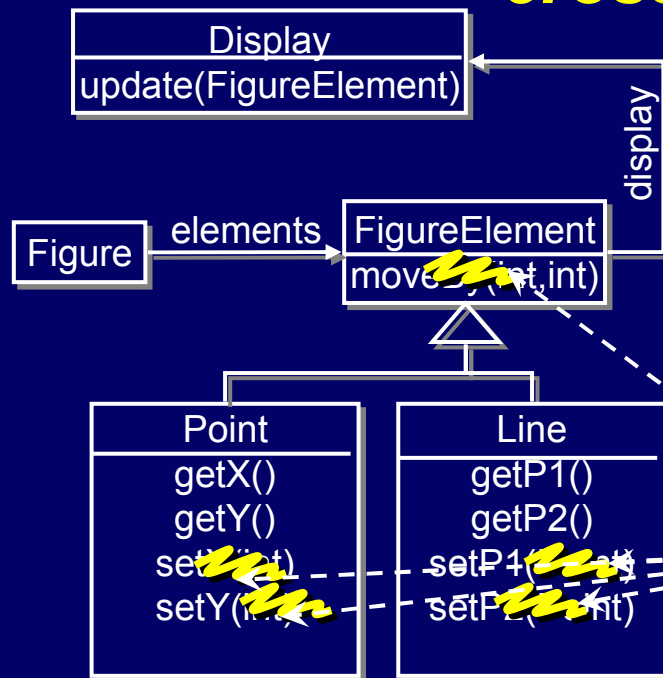
modeling crosscutting in aspect-oriented mechanisms

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aspect-oriented programming

- AOP supports modularization of **crosscutting concerns** [Kiczales et al.1997]



- e.g., a drawing editor & a concern: update display when figure moves

• **w/o AOP** vs. **w/ AOP**

```
DisplayUpdating
update(FigElm)
after(e) : update(FigElm) {
    e.display.update(e)
}
```

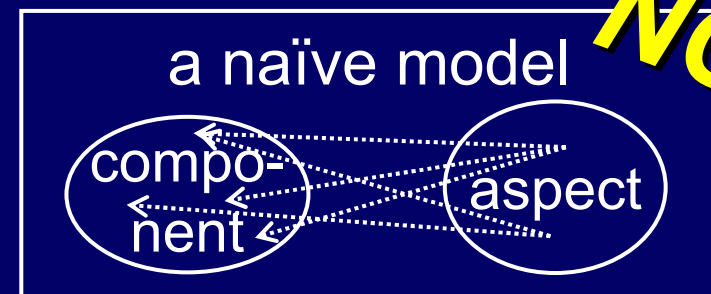
(so called) **components**

aspects

what's the essence of AOP?

- a naïve model does not capture
 - symmetric mechanism in Hyper/J
 - dynamic mechanism in AspectJ
 - more specialized mechanisms (e.g., Demeter)
 - ...

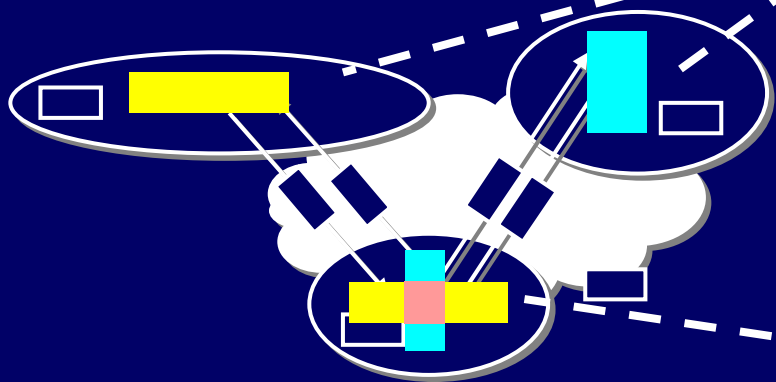
- we'd like to find a model
 - general enough to capture many mechanisms
 - not too general so that we can see the nature of AOP



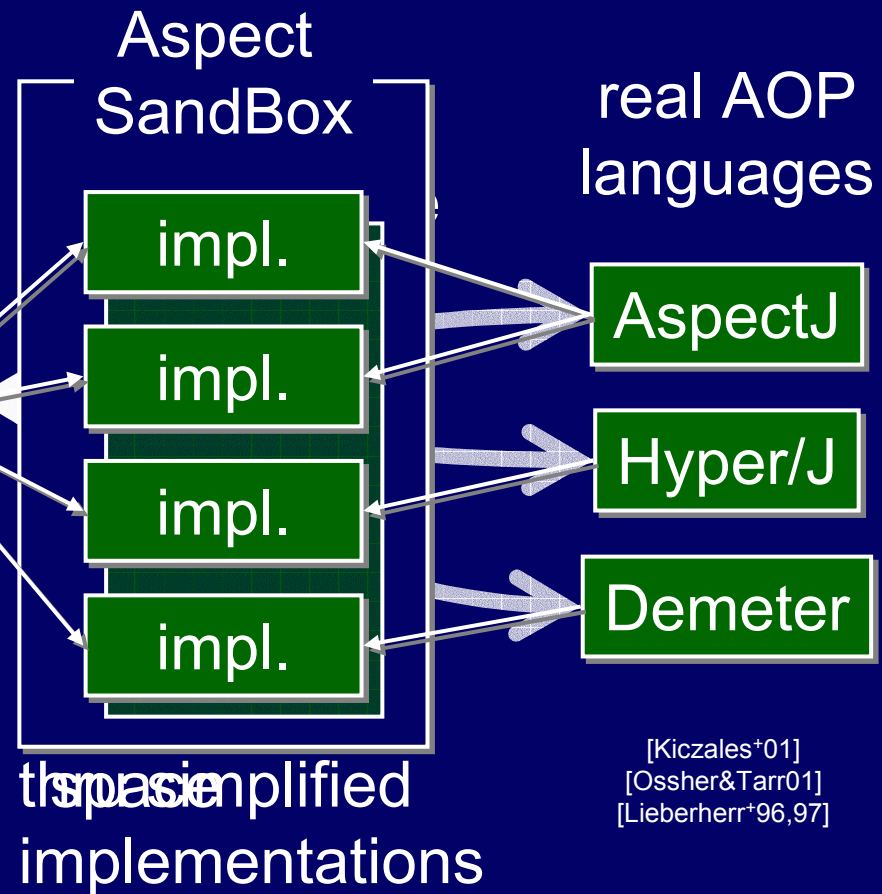
crosscutting!

contributions & approach

1. provide a common modeling framework



2. explain modular crosscutting



[Kiczales⁺01]
[Ossher&Tarr01]
[Lieberherr⁺96,97]

talk outline

- implementations of core AOP mechanisms
 - PA: an AspectJ-like (dynamic) mechanism
 - COMPOSITOR: a Hyper/J-like mechanism
 - (TRAV: a Demeter-like mechanism)
 - (OC: an AspectJ-like (static) mechanism)
- the modeling framework
- modular crosscutting
 - in terms of the modeling framework

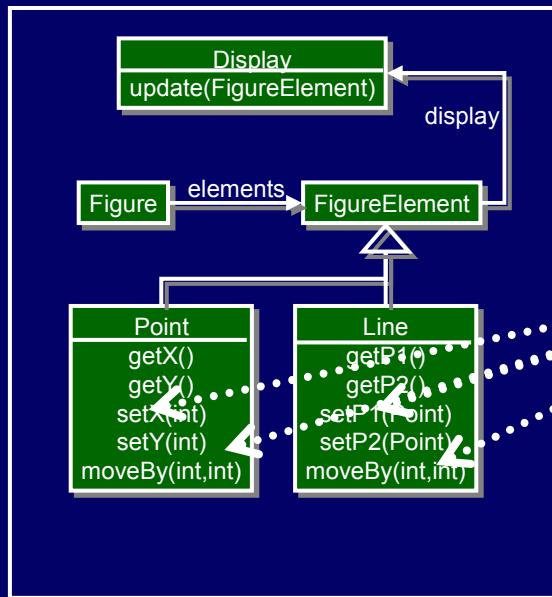
PA – pointcuts and advice

- simplified from (dynamic part of) AspectJ [Kiczales01]

- key elements:

- join point: **point in execution**
i.e., a method call

an example advice:
update display
after moving
any element



ifies when after():
es
t to do

erior
dularity

```
call(void Point.setX(int))
|| call(void Point.setY(int))
|| call(void Line.setP1(Point))
|| call(void Line.setP2(Point)) {
display.update();
}
```

PA: implementation

```
(define eval-exp
  (lambda (exp env)
    (cond ((call-exp? exp)
           (call-method (call-exp-mname exp)
                        (eval-exp (call-exp-obj exp) env)
                        (eval-rands (call-exp-rands exp) env)
                        ...)))
          ...)))
```

```
(define-struct call-jp (mname target args))
```

```
(define call-method
  (lambda (mname obj args)
    (let* ((jp (make-call-jp mname obj args))
           (method (lookup-method jp))
           (advice (lookup-advice jp)))
      (execute-advice advice jp
                      (lambda ()
                        (execute-method method jp))))))
```

an interpreter (à la EOPL)

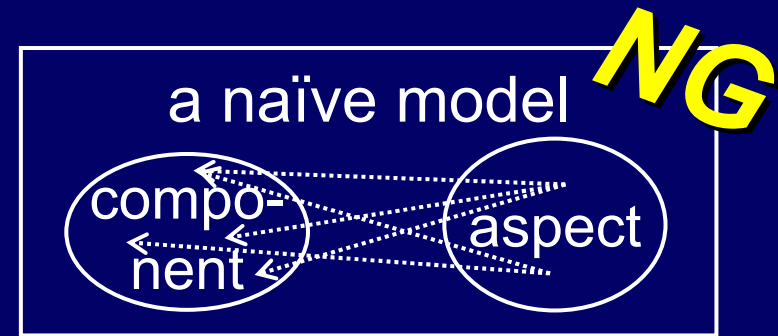
a join point represents a
method call

a method call is to:

- create a join point
- identify a method
- identify advice decls.
- execute advice decls.
- execute method

observations from PA implementation

- method and advice are treated similarly:
lookup & execute
→ symmetric model

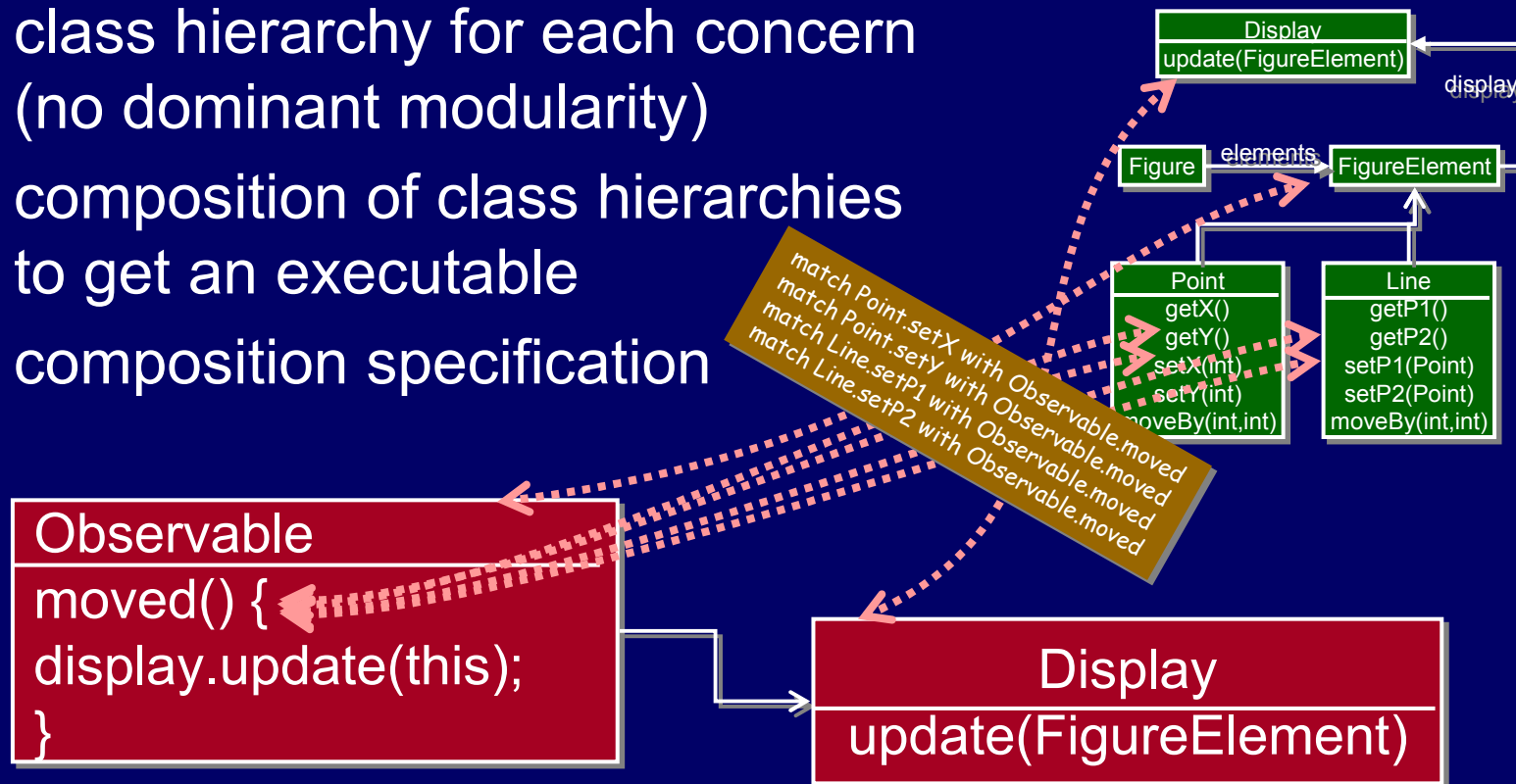


- join points come from execution
→ “weaving into components” is not good
→ weaving in the third space
(i.e., execution)

COMPOSITOR – class composition

simplified from Hyper/J [Ossher01]

- class hierarchy for each concern (no dominant modularity)
- composition of class hierarchies to get an executable
- composition specification

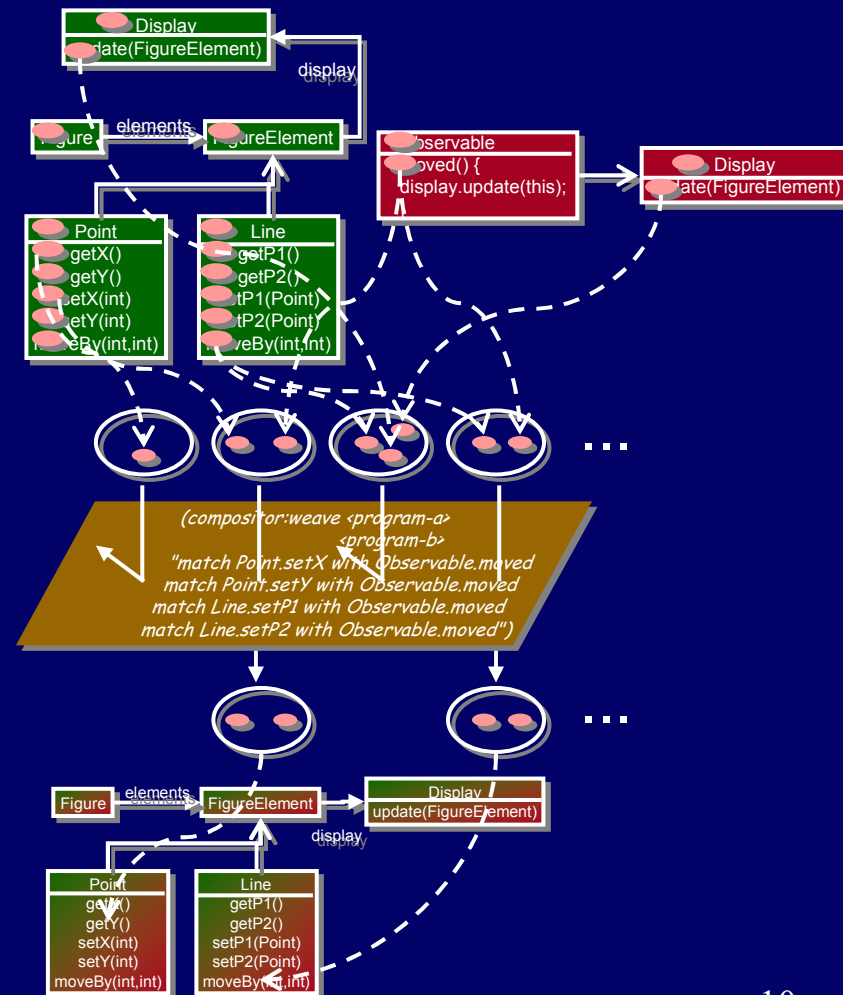


COMPOSITOR: implementation

source-to-source
translation

1. computes all possible combinations *
2. determines whether each should be merged
3. merges bodies & adds to program

(* very naïve approach;
just for explanation)



COMPOSITOR: implementation

```
(define compositor:weave
  (lambda (pgm-a pgm-b relationships)
    (let loop ((pgm (make-program '()))
              (seeds (compute-seeds pgm-a pgm-b)))
      (if (not (null? seeds))
          (let ((signature (all-match (car seeds)
                                      relationships)))
              (if signature
                  (let* ((jp (car seeds))
                        (decl (merge-decls jp relationships)))
                    (loop (add-decl-to-pgm decl pgm signature)
                          (remove-subsets jp (cdr seeds))))
                      (loop pgm (cdr seeds))))
          pgm))))
```

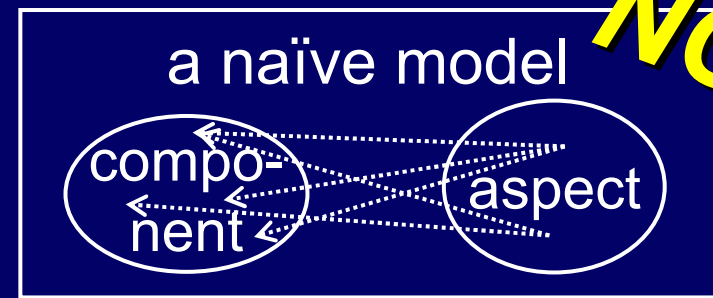
generate combinations
of methods

test all methods
have matching
signatures

merge method
bodies
and install

observations from COMPOSITOR implementation

- no dominant modularity
→ symmetric model
- join points are not only



- from pgm-a (nor pgm-b)
→ “weaving into components” is not good
→ weaving in the third space
- matching rule can be modified
→ weaving parameters

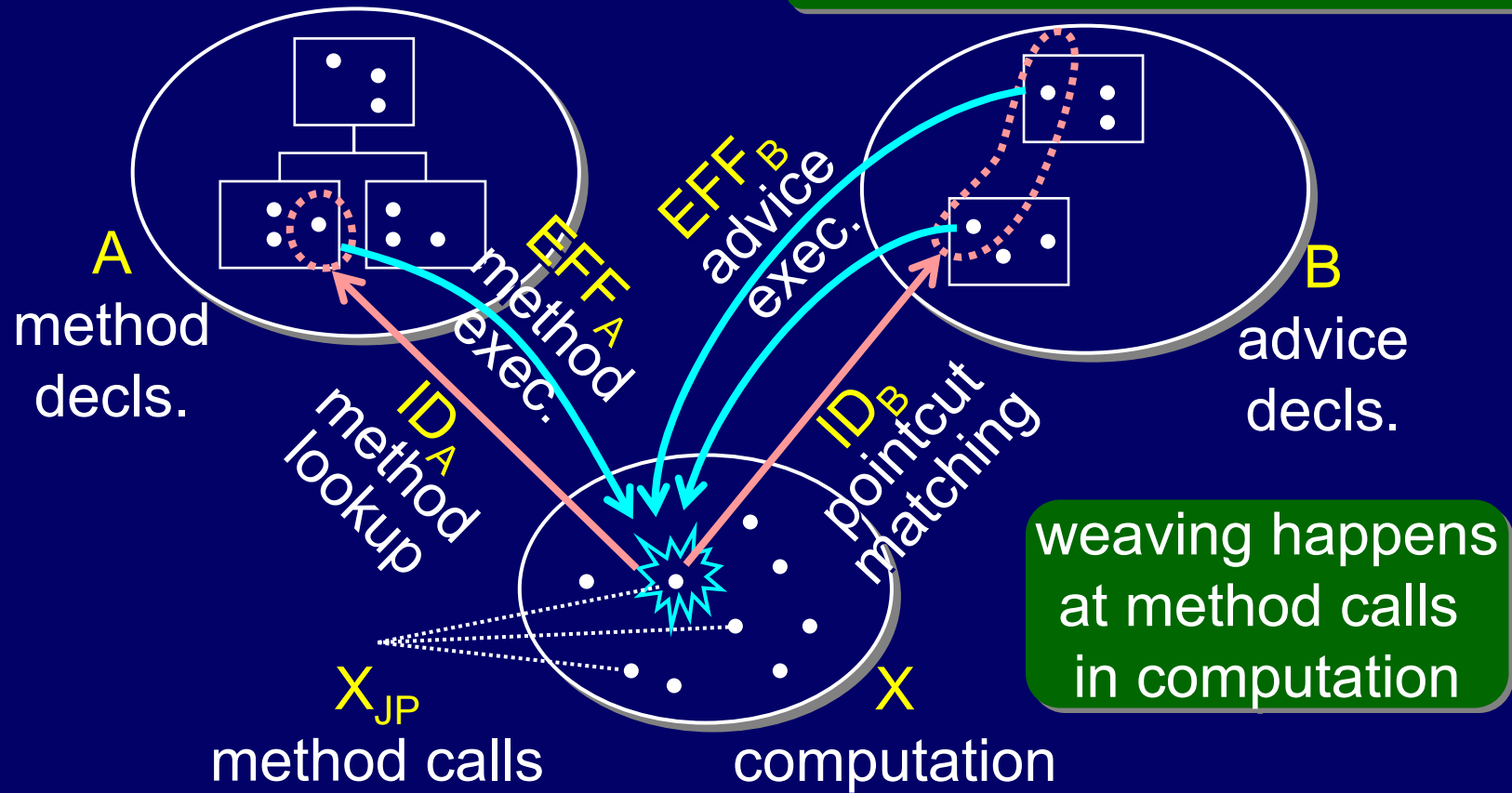
TRAV & OC

similarly implemented

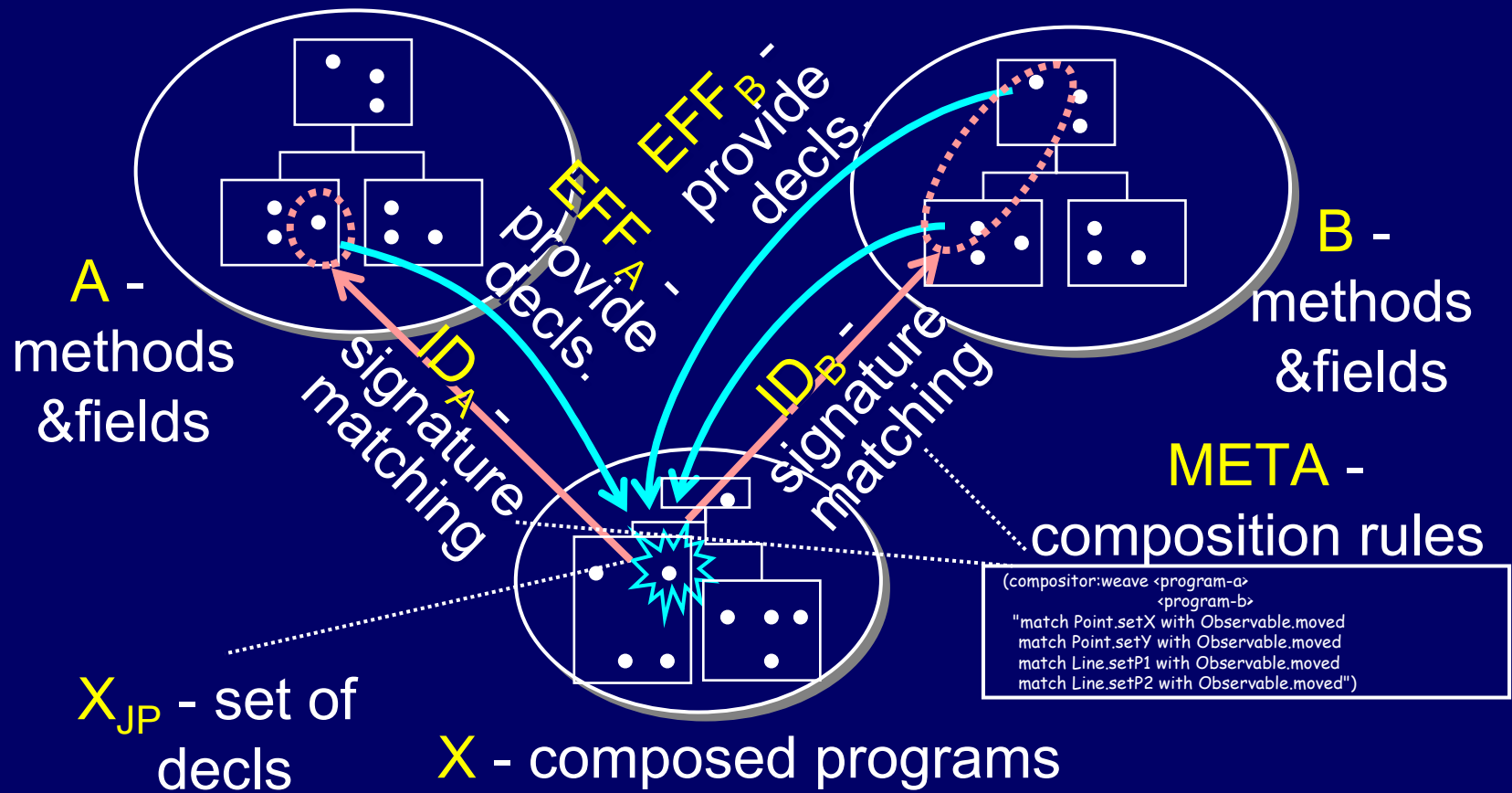
- TRAV: Demeter/DemeterJ/DJ [Liberrherr97], etc.
 - traversals through object graphs
 - modular specification: “where to go” & “what to do” otherwise scattered over classes
- OC: AspectJ’s introductions or ITD [Kiczales01]
(also in Flavors, etc. [Cannon82]...)
 - can declare methods/fields outside of the class declarations

the modeling framework: PA's case

method & advice are parallel

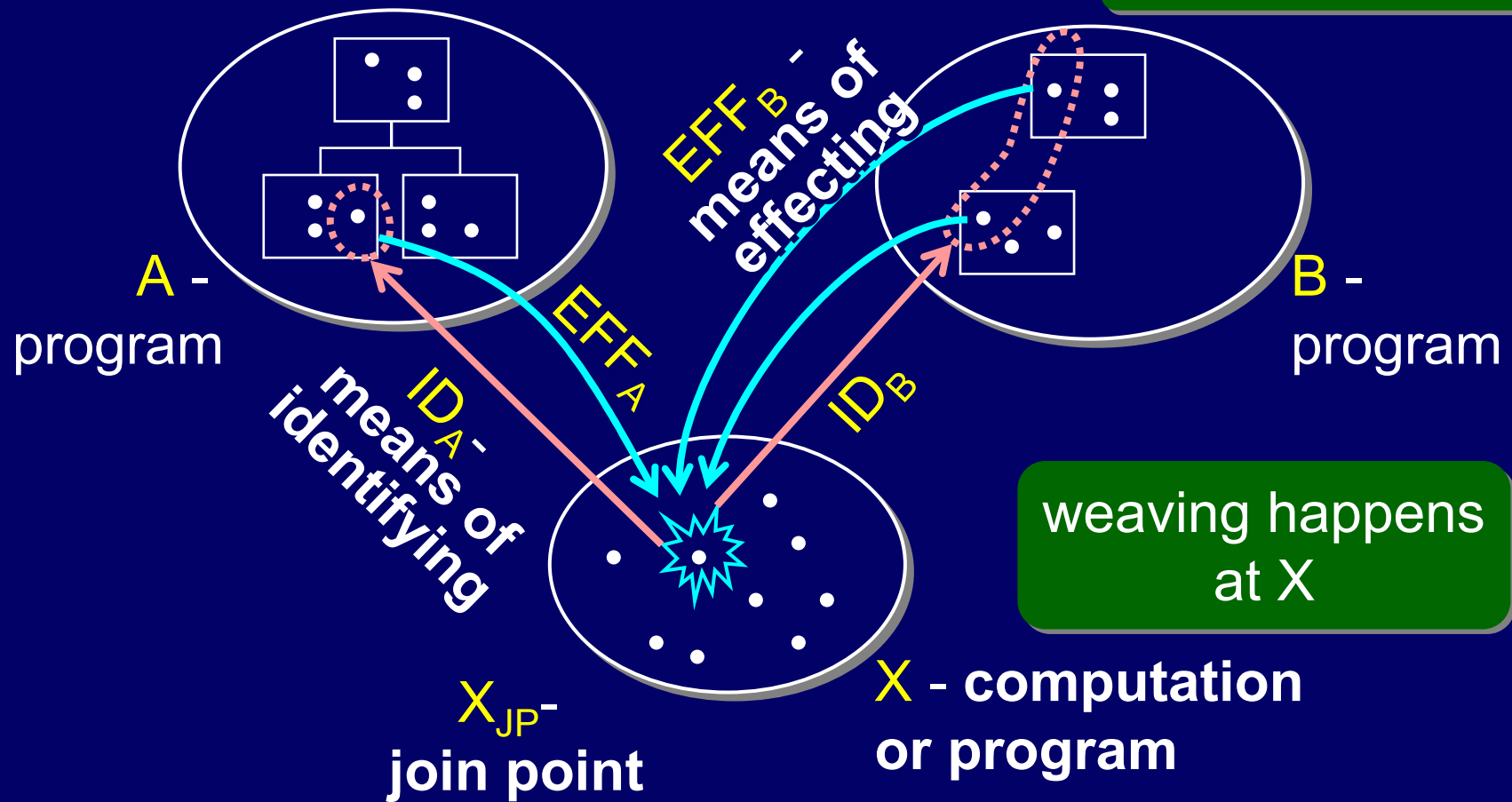


modeling framework: COMPOSITOR's case



the modeling framework

A&B are parallel



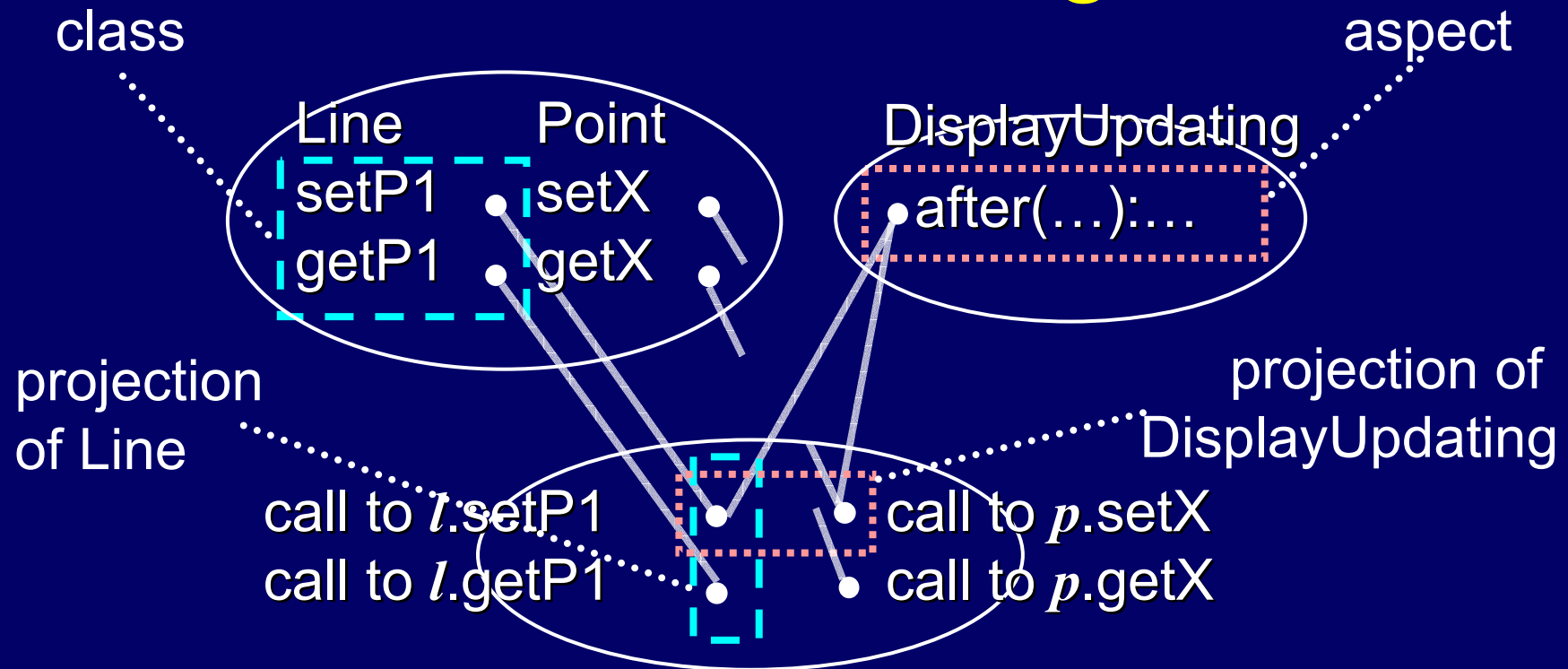
models for 4 mechanisms

	PA	TRAV	COMPOSITOR	OC
X	program execution	traversal execution	composed program	combined program
X _{JP}	method calls	arrival at each object	declarations in X	class declarations
A	c, m, f declarations	c, f declarations	c, m, f declarations	c declarations w/o OC declarations
A _{ID}	m signatures, etc.	c, f signatures	c, m, f signatures	method signatures
A _{EFF}	execute method body	provide reachability	provide declarations	provide declarations
B	advice declarations	traversal spec. & visitor	(= A)	OC method declarations
B _{ID}	pointcuts	traversal spec.	(= A _{ID})	effective method signatures
B _{EFF}	execute advice body	call visitor & continue	(= A _{EFF})	copy method declarations
META	none	none	match & merge rules	none

what's modular crosscutting?

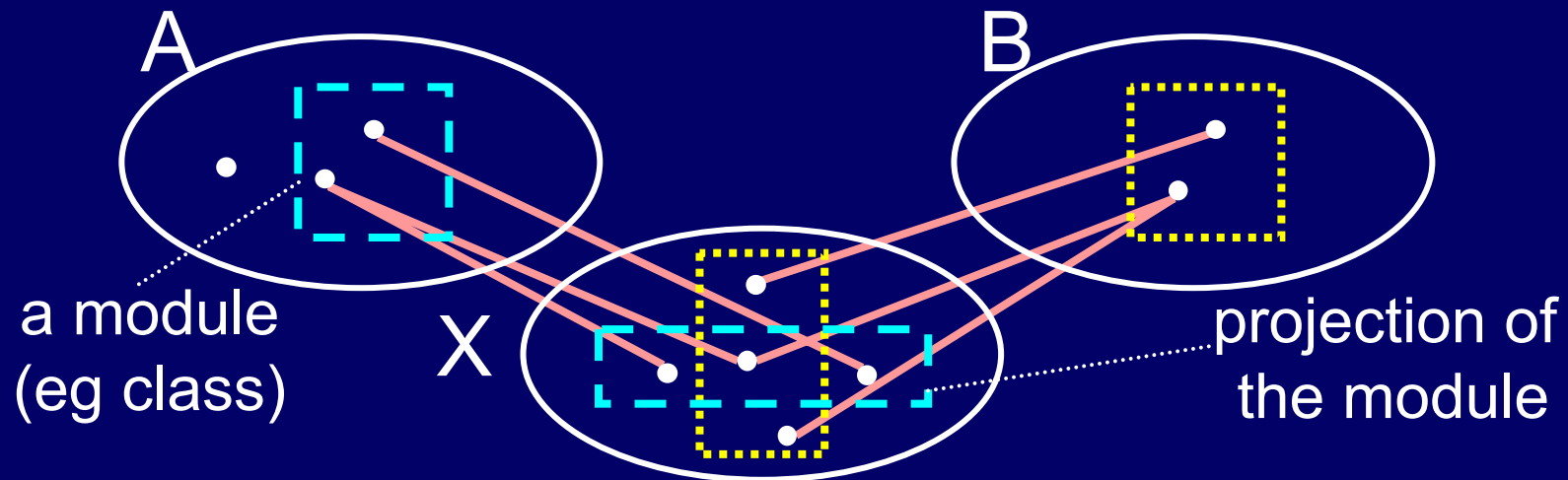
- it is said:
“AOP supports modular crosscutting”
but what is it?
- the modeling framework can explain:
two modules in A&B crosscut when
***projections of the modules
into X intersect and
neither is subset of the other***

an example of modular crosscutting in PA



“Line and DisplayUpdating crosscut in the execution”

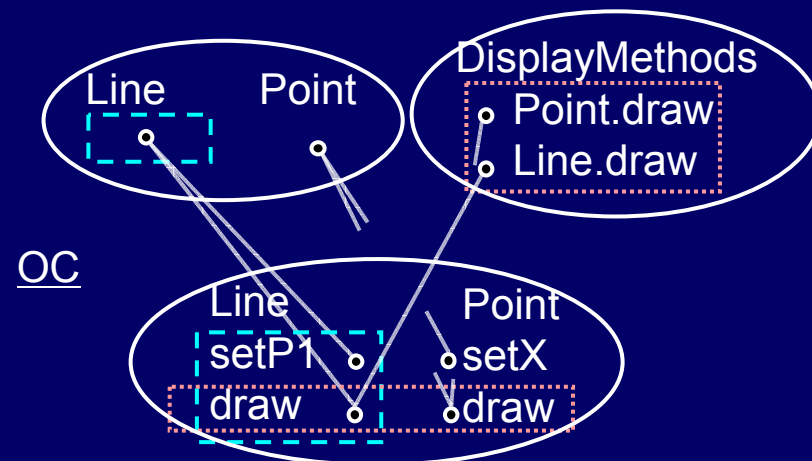
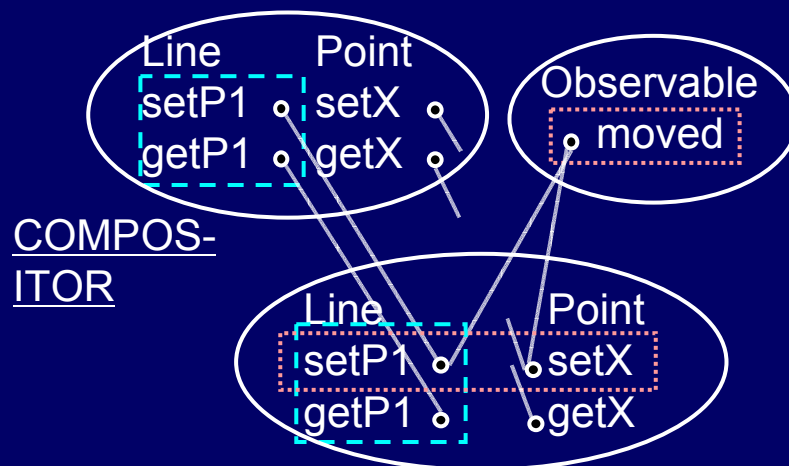
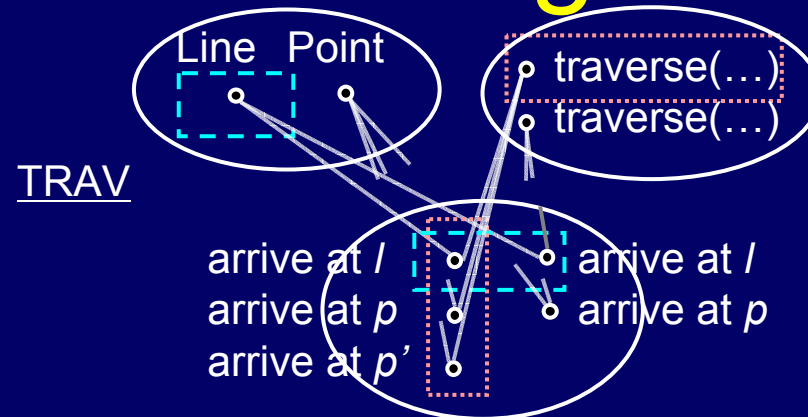
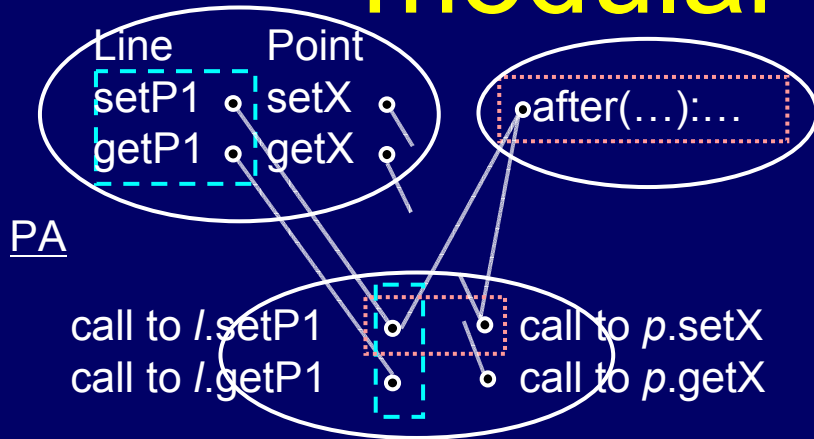
what's modular crosscutting?



two modules in A&B crosscut when
***projections of the modules
into X intersect and
neither is subset of the other***

lines are missing
in proceedings

examples of modular crosscutting



related work

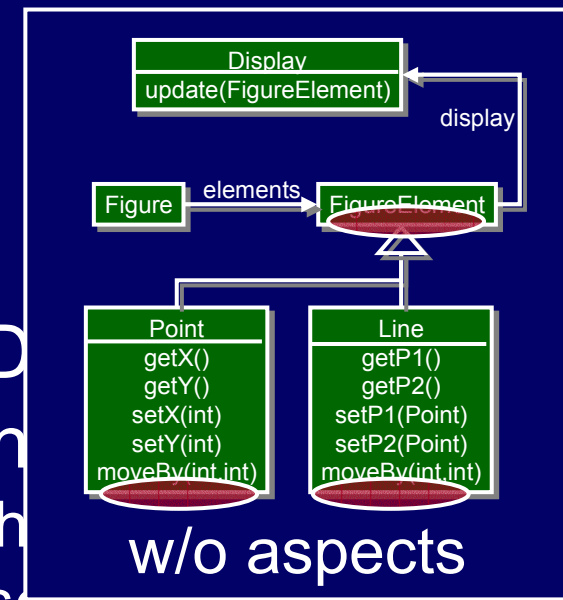
- comparison **two** AOP mechanisms;
e.g., Demeter vs. AspectJ [Lieberherr97]
- formal models for **particular** AOP mechanism
[Wand+01], [Lämmel01], etc.
- Filman-Friedman's claim on non-invasiveness,
or "quantified assertions over programs
written by oblivious programmers"
 - not explicit in our framework;
suggesting invasive AOP mechanisms is possible

summary

- 3 part modeling framework
 - elements from A&B meet at JP in X
 - based on executable implementations
www.cs.ubc.ca/labs/spl/projects/asb.html
- explanation of modular crosscutting
 - in terms of projections of A&B modules into X
- future work:
 - discuss more features in AOP on the framework
e.g., non-invasiveness, remodularization, ...
 - unified implementation and formalization
 - apply to foundational work: semantics_[Wand01,02],
compilation_[Masuhara02,03], new feature designs...

TRAV – traversals

- based on Demeter/DemeterJ/D
- traversals through object graph
 - specification: “where to go” & “what to do”
 - otherwise scattered among classes
- e.g., counting FigureElements in a Figure



```
Visitor counter = new CountElementsVisitor();
counter.traverse("from Figure to FigureElement",
               fig,
               counter);
```

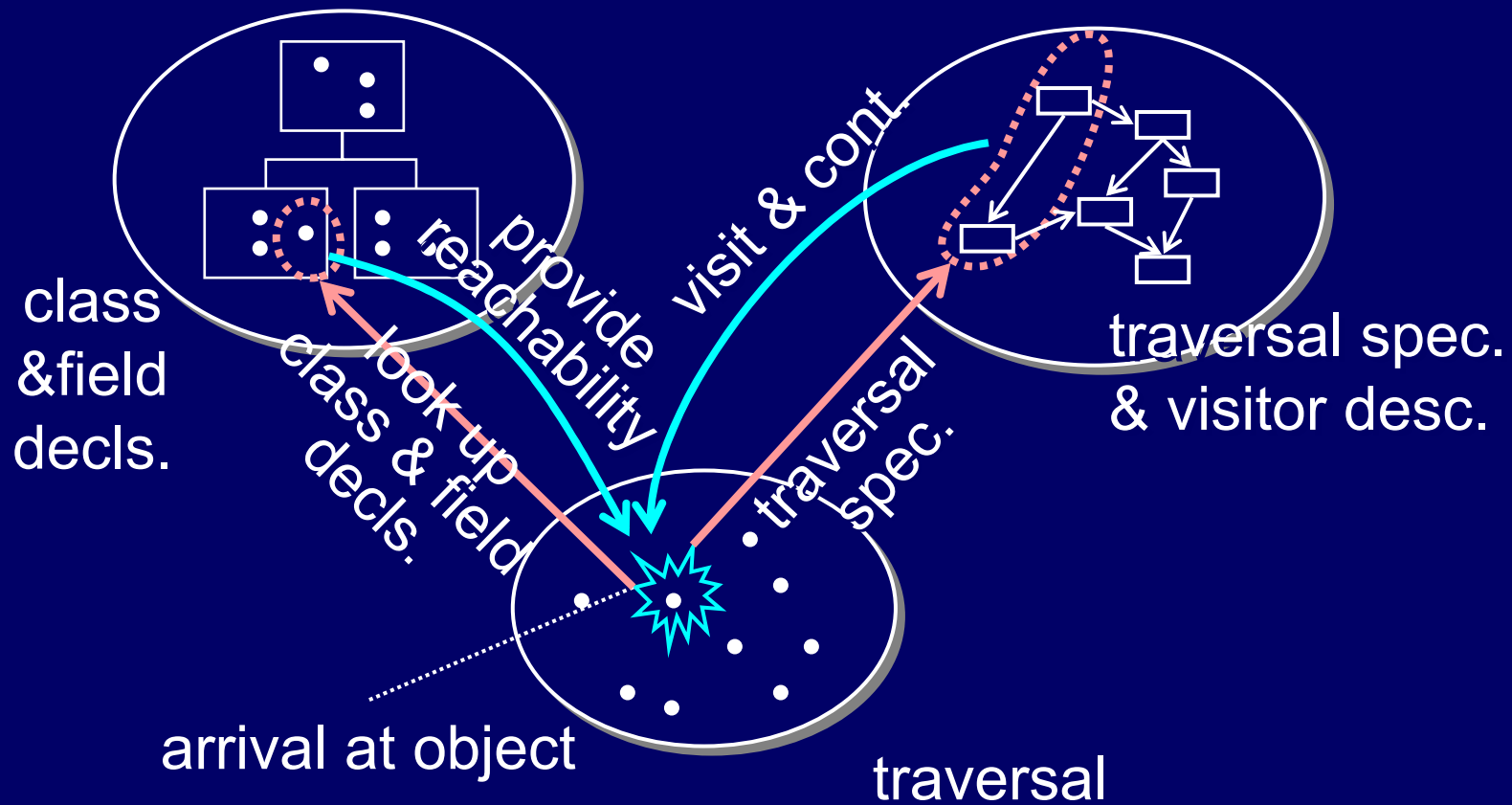

implementation of TRAV

- weaver = traversal engine

```
(define trav:weave
  (lambda (trav-spec root visitor)
    (let arrive ((obj root)
                 (path (make-path (object-cname root))))
      (call-visitor visitor obj)
      (for-each (lambda (fname)
                  (let* ((next-obj (get-field fname obj))
                        (next-cname (object-cname next-obj))
                        (next-path (extend-path path
                                              next-cname)))
                    (if (match? next-path trav-spec)
                        (arrive next-obj next-path))))
                (object->fnames obj))))))
```

- visit object
- match path vs. spec
- and cont.

model for TRAV



OC – open classes

- based on AspectJ's introductions [Kiczales01]
Flavors, etc. [Cannon82]...
- can declare methods/fields
outside of the class declarations
- example: add drawing functionality

```
class DisplayMethods {  
    void Point.draw() { Graphics.drawOval(...); }  
    void Line.draw() { Graphics.drawLine(...); }  
}
```

implementation of OC

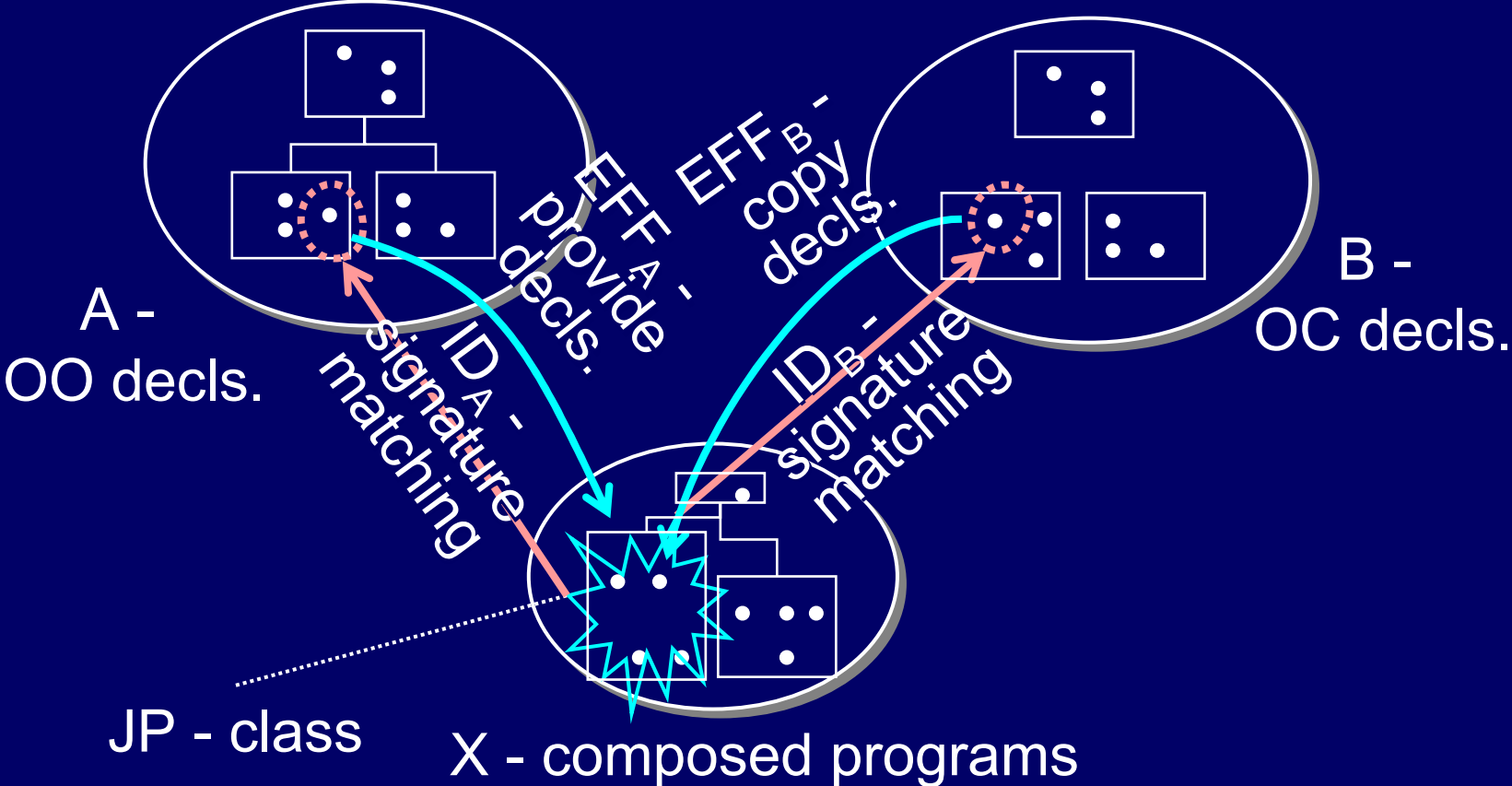
- a special case of COMPOSITOR
 - a source-to-source translator
 - class decls \times oc decls \rightarrow program

```
(define oc:weave
  (lambda (pgm):-> pgm
    (let ((pgm      (remove-oc-mdecls pgm))
          (oc-mdecls (gather-oc-mdecls pgm)))
      (make-pgm
        (map (lambda (cdecl)
              (let* ((cname (class-decl-cname cdecl))
                    (sname (class-decl-sname cdecl))
                    (per-class-oc-mdecls
                     (lookup-oc-mdecls cname oc-mdecls)))
                (make-class-decl cname sname
                  (append (class-decl-decls cdecl)
                          (copy-oc-mdecls cname per-class-oc-mdecls))))))
          (pgm-class-decls pgm))))))
```

- A
- B
- a new program in X
- cdecl is a jp

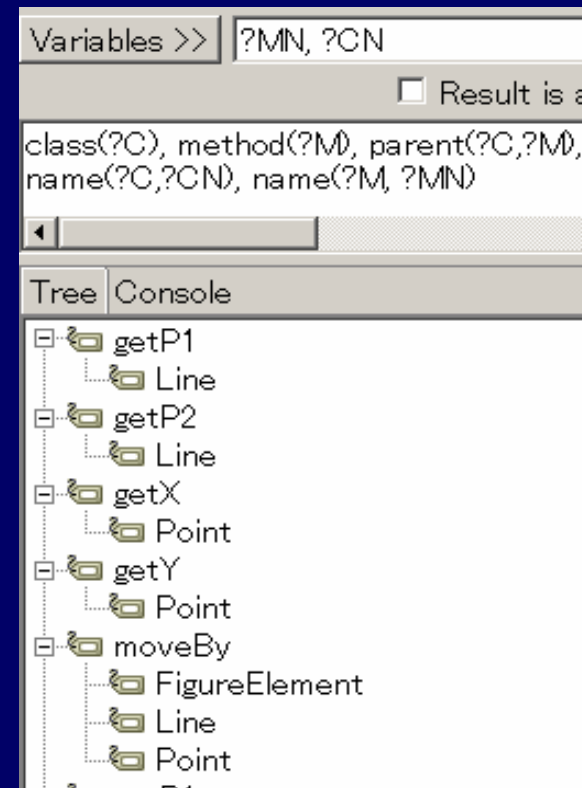
- ID_B
- EFF_A and EFF_B

model for OC



QB – query-based browser

- a customizable code exploration tool [Rajagopalan02]
- takes parameters:
 - properties to extract
 - order of properties
- can give different views of a program;
e.g., group classes by method names



QB – query-based browser

Variables >> ?CN, ?MN

Result is a

class(?C), method(?M), parent(?C,?M),
name(?C,?CN), name(?M, ?MN)

Tree Console

update

classes with defined methods

- getP2
- moveBy
- setP1
- setP2
- Point
 - getX
 - getY

Variables >> ?MN, ?CN

Result is a

class(?C), method(?M), parent(?C,?M),
name(?C,?CN), name(?M, ?MN)

Tree Console

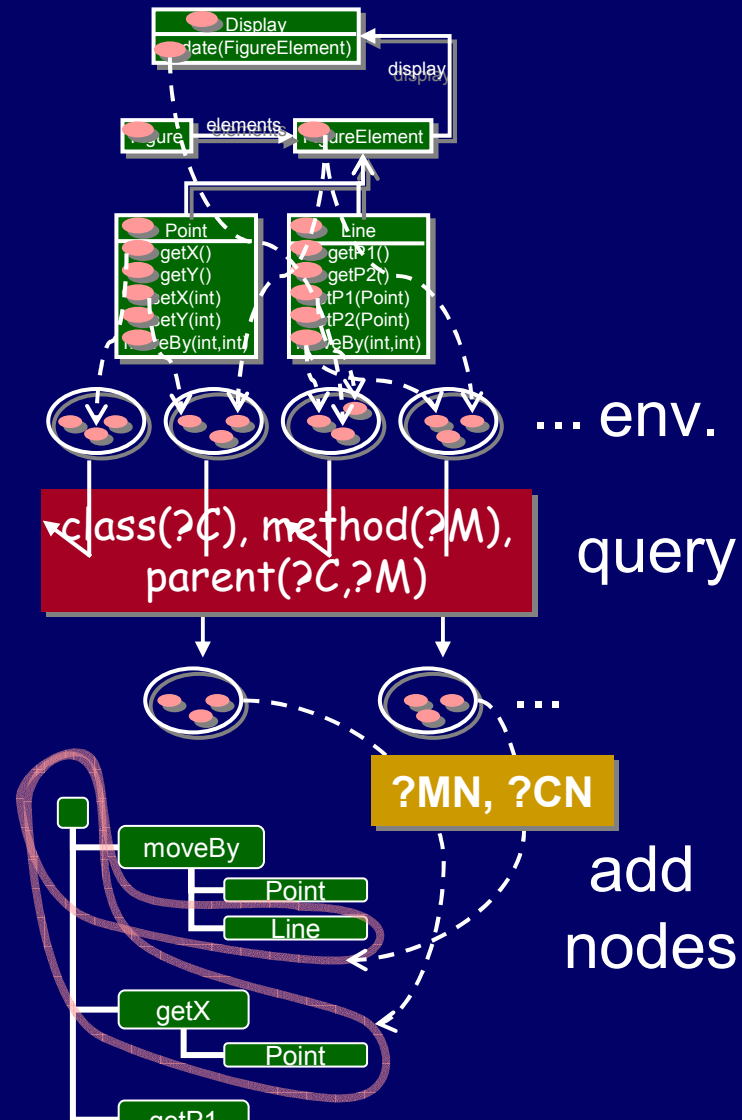
getP1

method names with defining classes

- getX
 - Point
- getY
 - Point
- moveBy
 - FigureElement
 - Line
 - Point

implementation of QB

1. extract metaobjects
2. build envs.
3. test query against each env
4. add nodes to tree guided by the var. list



implementation of QB

```
(define qb:unweave
  (lambda (pgm query tree-vars);->tree
    (let* ((metaobjects (elaborate-program pgm))
          (all-envs (possible-envs (query-vars query)
                                   metaobjects))

          (tree (make-empty-tree)))
      (for-each (lambda (env)
                  (if (match? env query)
                      (let ((vals (map (lambda (var)
                                         (lookup-var var env))
                                       tree-vars)))
                          (add-to-tree! vals tree))))
                all-envs)
              tree)))
```

- A to isomorphic X
- tuples of jps
- B
- ID_B
- EFF_B
- return B

model for QB

